

AVVISO DI SEMINARIO

Martedì 1 dicembre 2015, ore 15.00

Sala Stampa—Aula Magna, Università della Calabria (CS)

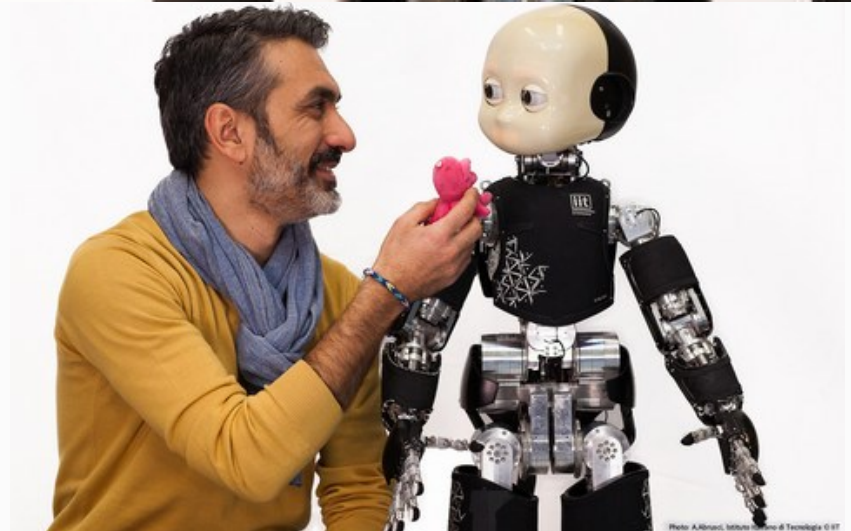
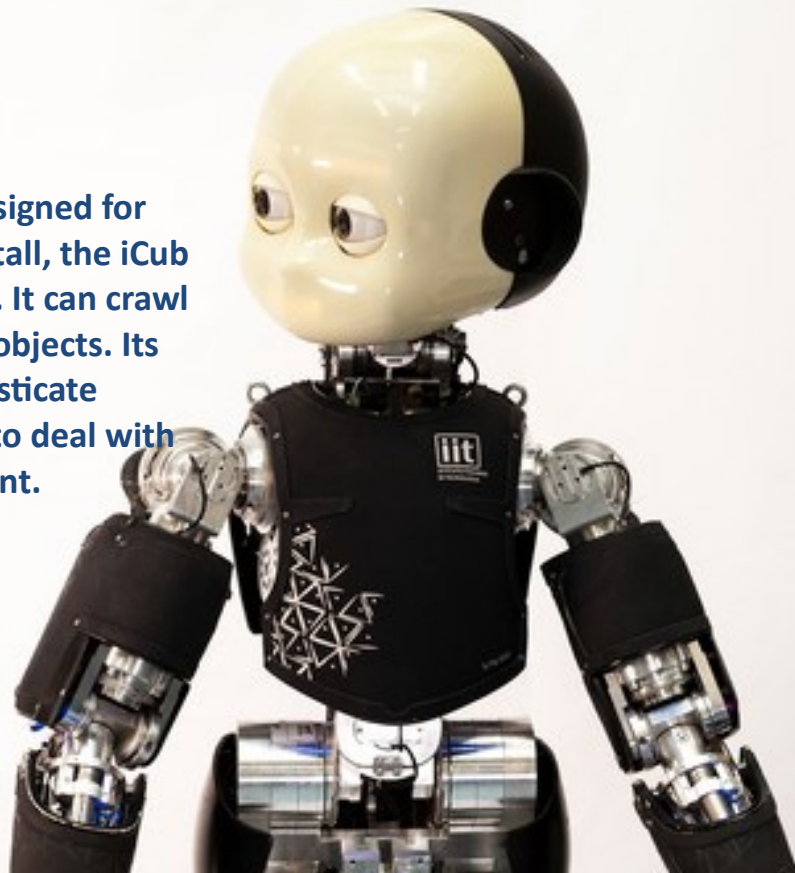
PROF. GIORGIO METTA

Istituto Italiano di Tecnologia (Genova)

iCub, an open source platform for research in robotics & AI

The iCub humanoid is a robotic platform designed for research in embodied cognition. At 104 cm tall, the iCub has the size of a four and half year old child. It can crawl on all fours, walk and sit up to manipulate objects. Its hands have been designed to support sophisticated manipulation skills. The iCub is sensorized to deal with the physical interaction with the environment.

It is distributed as Open Source following the GPL/LGPL licenses and can now count on a worldwide community of enthusiastic developers. It is one of the few platforms in the world with a sensitive full-body skin.



Docenti, ricercatori e studenti sono invitati a partecipare



ISTITUTO
ITALIANO DI
TECNOLOGIA

Organizzato da
Prof. Alessandro Casavola (DIMES)
Dr. Francesca Stramandinoli (IIT)

UNIVERSITÀ DELLA CALABRIA



DIMES - Dipartimento di INGEGNERIA INFORMATICA
MODELLISTICA, ELETTRONICA E SISTEMISTICA